

# AdaRadar: Rate Adaptive Spectral Compression for Radar-based Perception

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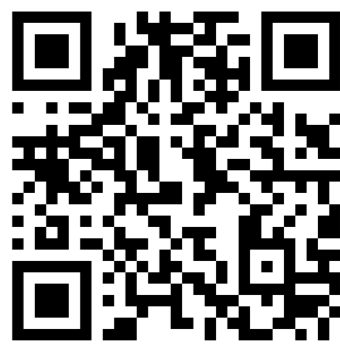
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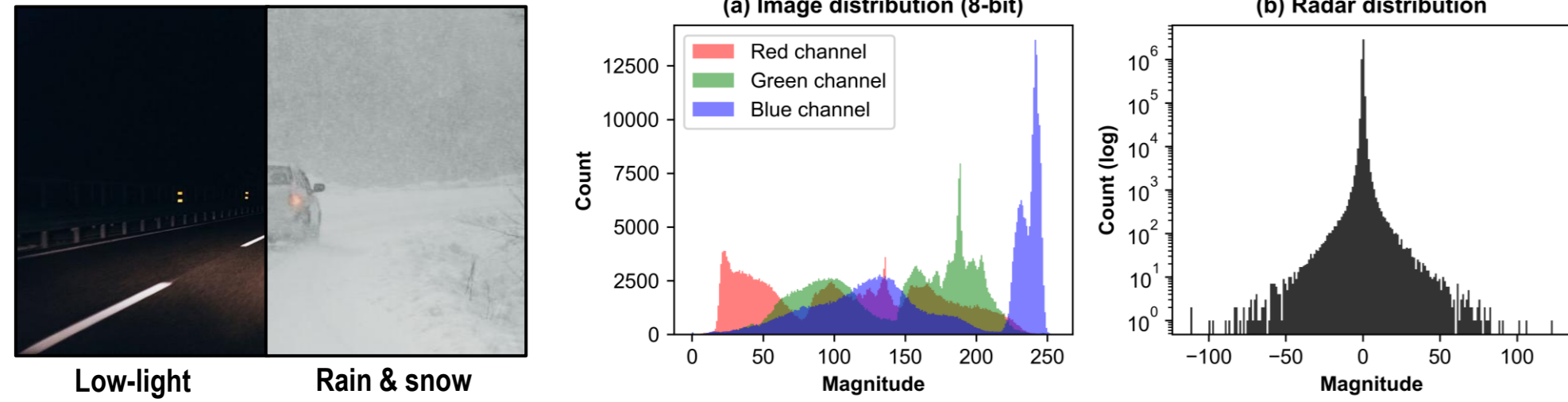


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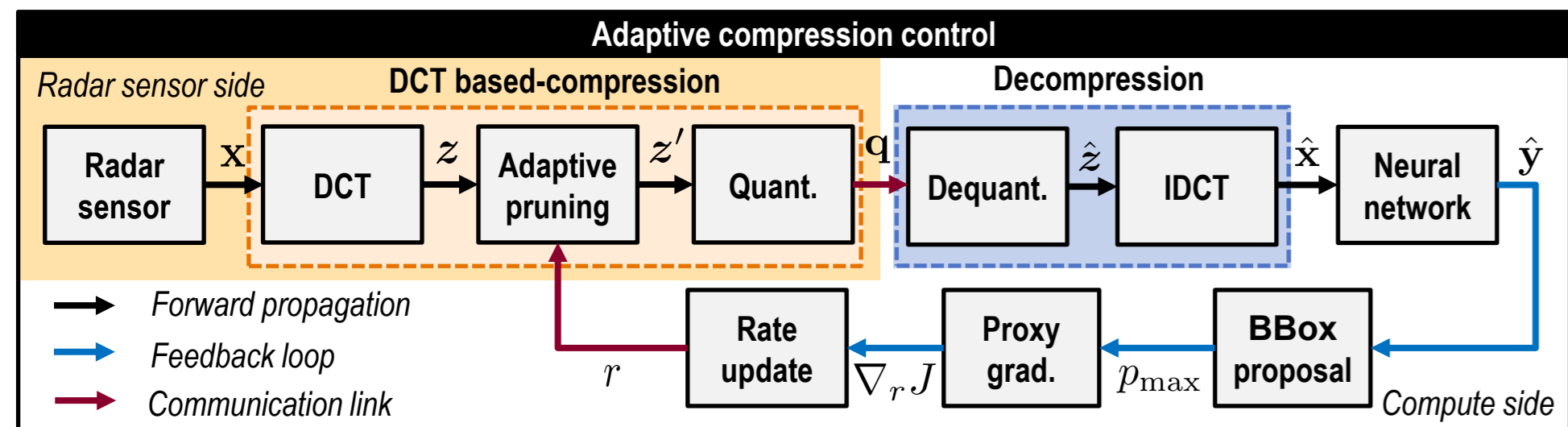
Project page

## Radar Complements Camera & LiDAR



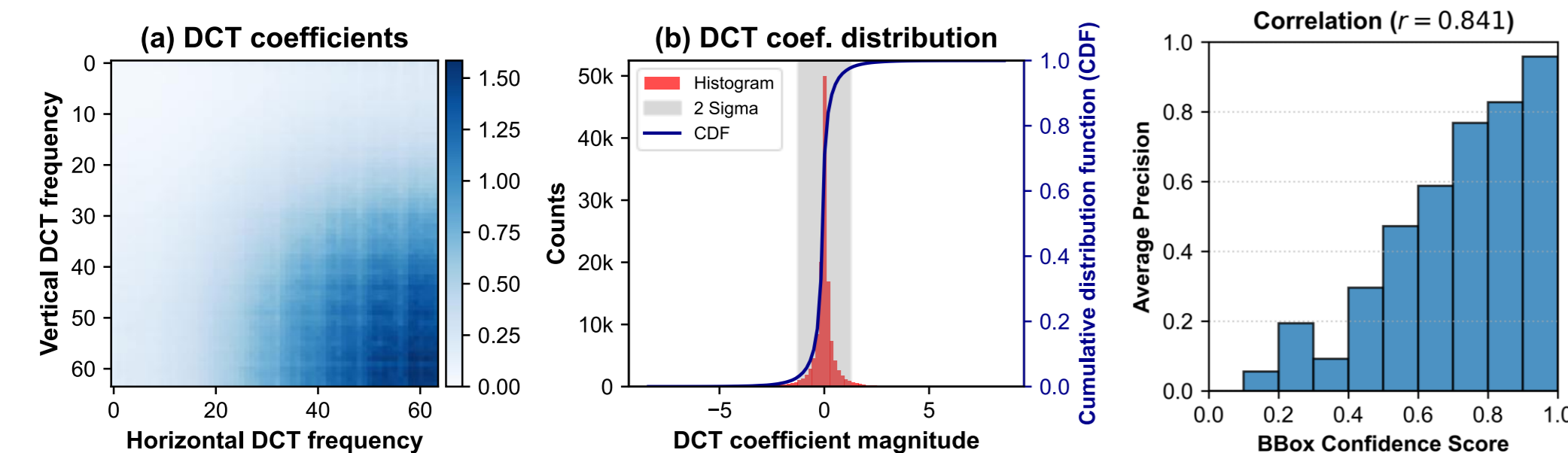
- Radar perception is a critical modality in autonomous driving, complementing camera & LiDAR.
- Natural images span a broad dynamic range.
- Radar signals exhibit extreme sparsity and a heavy-tailed profile (1st/99th percentiles at  $\pm 1.74$ ).

## Adaptive Compression Rate Control



- Our proposed method introduces a **feedback loop** in which the proxy gradient is computed from the detection outputs to update the compression ratio adaptively.
- This avoids the need for **backpropagation** through the communication channel.
- DCT-based compression on the radar sensor side and decomposition on the compute side.

## Motivation for Compression & Adaptation



- The DCT coefficient **magnitudes** are clustered in the high-frequency bins.
- Their histogram is sharply peaked—strong **sparsity** and clear opportunities for compression.
- BBox confidence shows great correlation with the ground truth label.

## Feedback with Proxy Gradient

Task objective:

$$\max_{\{r_t\}_{t=1}^T} \mathbb{E}[J_t(r_t)], \quad J_t(r_t) = h(\mathbf{x}_t, r_t) - \lambda \cdot B(r_t)$$

hyper-parameter to control accuracy-bandwidth trade-off  
 Instantaneous bit-rate

Gradient w.r.t bit-rate ( $r$ ):

$$\nabla_r J = \nabla_r h(\mathbf{x}, r) - \lambda \cdot B'(r)$$

Proxy gradient:

$$\hat{\nabla}_r h(\mathbf{x}, r) \approx \frac{h(\mathbf{x}, r) - h(\mathbf{x}, r - \epsilon)}{\epsilon} = \frac{p - p^-}{\epsilon}$$

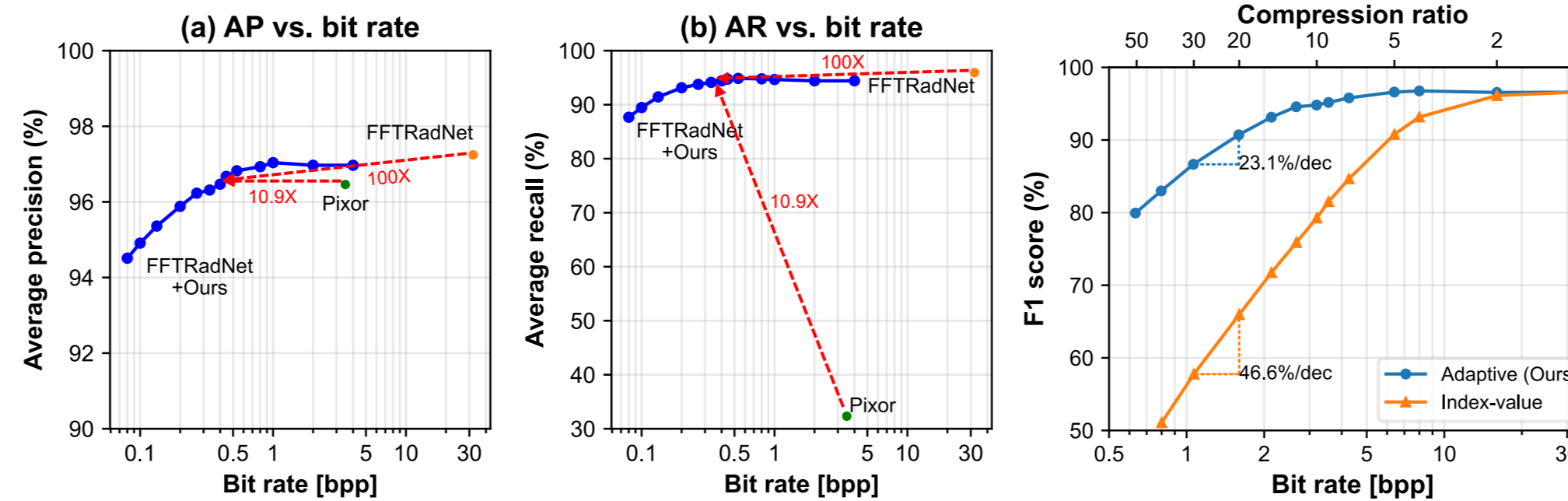
- Task objective:  $h$  encapsulates compression, decompression, forward inference, and BBox proposal.

### Algorithm 1: Adaptive rate control

**Input:** Radar sequence  $\{\mathbf{x}_t\}_{t=1}^T$ , weight ( $\Theta$ ), initial pruning ratio ( $r_1$ ), learning rate ( $\eta$ ), perturbation ( $\epsilon$ )  
**Output:** Detection map  $\{\hat{\mathbf{y}}_t\}_{t=1}^T$

- for  $t := 1$  to  $T$  do
- $\mathbf{q}_t, \mathbf{Q}_t \leftarrow \text{Compression}(\mathbf{x}_t, r_t)$ ;  
 // Transfer  $\{\mathbf{q}, \mathbf{Q}\}$  once
- $\hat{\mathbf{x}}_t \leftarrow \text{Decompression}(\mathbf{q}_t, \mathbf{Q}_t)$ ;
- $\hat{\mathbf{y}}_t \leftarrow f_{\Theta}(\hat{\mathbf{x}}_t)$ ; **Network inference pass #1**
- $\{(b_k, p_k)\}_{k=1}^K = \text{Propose}(\hat{\mathbf{y}}_t)$ ;
- if adaptive then**
- $\mathbf{q}_t^- \leftarrow \text{Pruning}(\mathbf{q}_t, \epsilon)$ ;
- $\hat{\mathbf{x}}_t^- \leftarrow \text{Decompression}(\mathbf{q}_t^-, \mathbf{Q}_t)$ ;
- $\hat{\mathbf{y}}_t^- \leftarrow f_{\Theta}(\hat{\mathbf{x}}_t^-)$ ; **Network inference pass #2**
- if  $k > 0$  then**
- $r_{t+1} \leftarrow r_t - \eta \hat{\nabla}_r J$ ;

## Rate-accuracy Trade-off



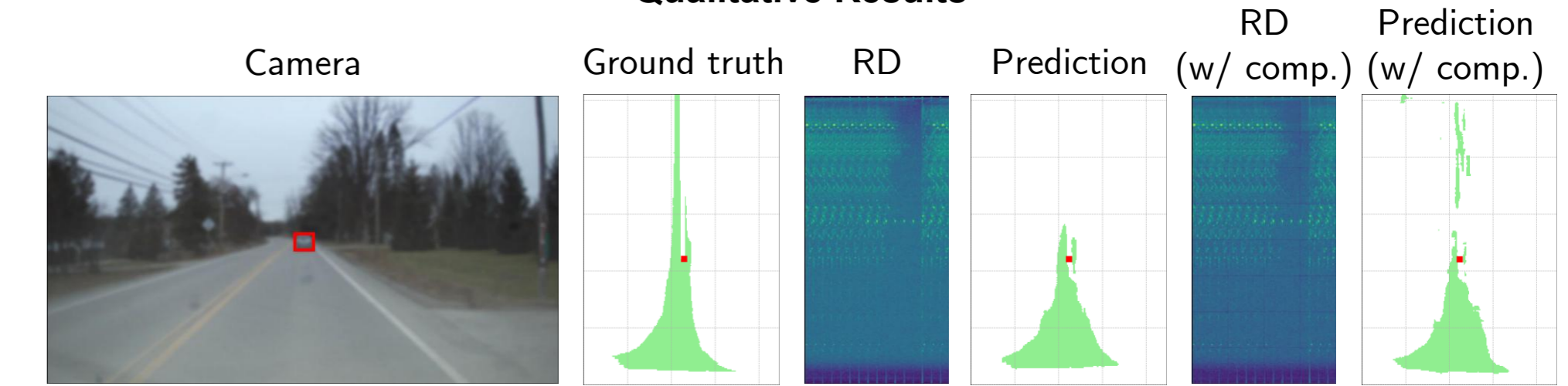
- Our compression scheme achieves **100x** reduction in the radar feature map size while having a **1%p decrease** in the performance compared to the baseline.
- Our method remains **stable** until 5x compression whereas the performance drop-off begins immediately with the index-value pair-based method.
- The roll-off gradient of **23.1%/dec** is much more gentle for the spectral pruning-based compression vs. **46.6%/dec** of the spatial-domain counterpart.

## Compression Results – RADial Dataset

Method	Bit	Prune ratio	Bit rate [bpp] ↓ (Comp. ratio ↑)	P (%) ↑	Detection R (%) ↑	F1 (%) ↑	Segment. mIoU (%) ↑
Baseline [2]	32	-	32 (1x)	97.24	95.93	96.58	75.97
+Index-value [11]	32	12x	2.67 (12x)	<b>97.55</b>	62.12	75.91	49.86
+Adaptive (Ours)	4	12.57x	<b>0.32 (101x)</b>	96.25	<b>94.04</b>	<b>95.13</b>	<b>79.34</b>

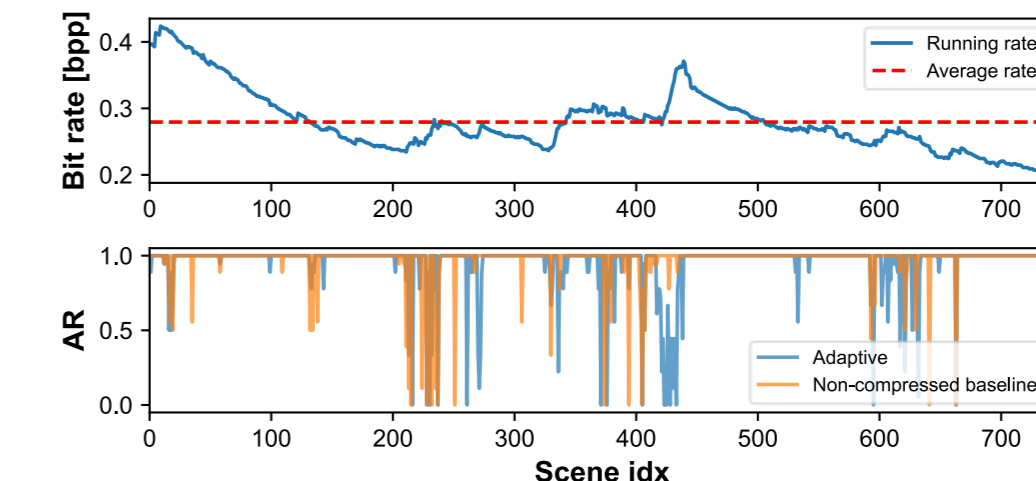
- An average pruning ratio of **12.57x** combined with **8x** gain from quantization, yields a bit rate of **0.32 bits per pixel (bpp)**, corresponding to a **101x** compression ratio.
- On the segmentation task, ours improves the performance by **4%**.
- Our method markedly **surpasses** index-value based method.

## Qualitative Results



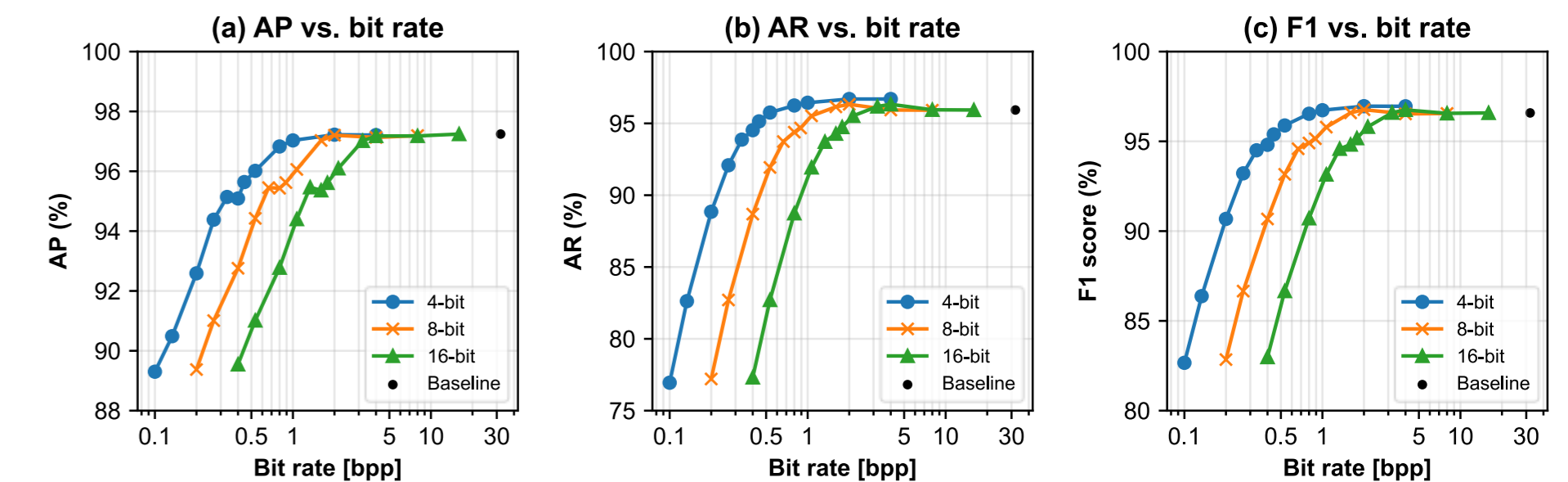
- Camera images provide contextual reference for the scene (not fed into network).
- The network predicts both **detection** and **segmentation** outputs.

## Time Series Analysis

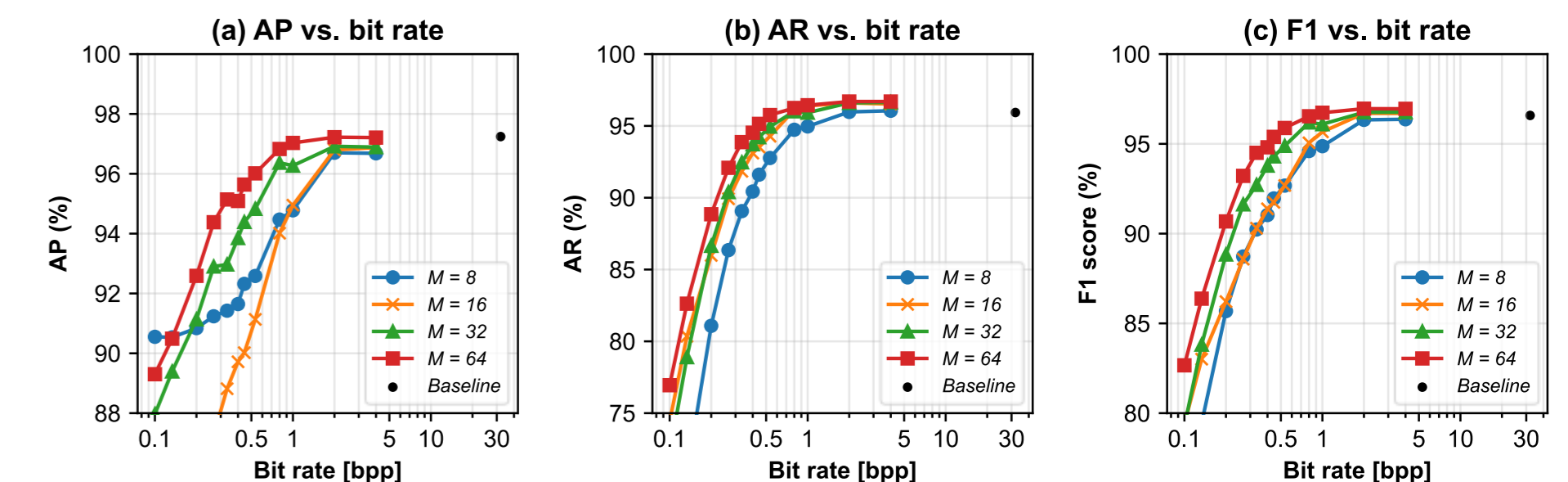


- We **visualize** the online compression with bit rate and detection metric.
- We expect that the controller decreases the pruning ratio to compensate for the AR drop.
- It achieves an average bit rate of **0.279 bpp** with 8-bit quantization, yielding a **115x** compression with AR of **93.91%**.

## Effect of Quantization Bit Width & DCT Block Length



- Quantization up to **4-bit** does not affect the performance compared to that of 8-bit and 16-bit. ( $M = 64$ )



- For the block-size sweep,  $M = 64$  yields the best trade-off between performance and overhead from the scaling factor. (bit width = 4-bit)